Notes: Flexible Imputation of Missing Data – Ch1 Introduction

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Multiple Imputation in a Nutshell

Concepts of MCAR, MAR, MNAR

- Missing completely at random (MCAR): the probability of being missing is the same for all cases
 - Cause of missing is unrelated to the data
- Missing at random (MAR): the probability of being missing only depends on the observed data
 - Cause of missing is unrelated to the missing values
- Missing not at random (MNAR): probability of being missing depends on the missing values themselves

Listwise deletion and pairwise deletion

- Listwise deletion (also called complete-case analysis): delete rows which contain one or more missing values
 - If data is MCAR, listwise deletion produces unbiased estimates of means, variances, and regression weights (if need to train a predictive model)
 - If data is not MCAR, listwise deletion can severely bias the above estimates.
- Pairwise deletion (also called available-case analysis)
 - Mean and variance of variable X are based on all cases with observed data on X
 - Covariance and correlation of X and Y is based on all data which both X and Y have non-missing values

Mean imputation

- Compared with the observed data, in the imputed data (observed + imputed values)
 - Standard deviations decrease
 - Correlation decreases
 - Means can be biased if the data is not MCAR.



Figure 1.2: Mean imputation of Ozone . Blue indicates the observed data, red indicates the imputed values.

Regression imputation

- 1. Build a regression model from the observed data
- 2. Impute the missing values in the response variable with the predicted values from the fitted regression
 - The impute values are the most likely values under the model
 - However, it decreases the variance of the target variable
 - And it increases the correlations between the target and covariates
 - Regression imputation, and its modern incarnations in machine learning is probably the most dangerous of all ad-hoc methods



Stochastic regression imputation

- 1. Build a regression model from the observed data
- 2. Impute a missing value in the response variable with the predicted value *plus a random draw from the residual*
 - Preserves variance and correlation.
 - Imputed values can exceed the range (e.g., a negative Ozone level). A more suitable model may resolve this.



Figure 1.4: Stochastic regression imputation of Ozone .

LOCF and BOCF

- Last observation carried forward (LOCF) and baseline observation carried forward (BOCF) are for longitudinal data.
- LOCF can yield biased estimation even under MCAR.



Figure 1.5: Imputation of Ozone by last observation carried forward (LOCF).

Indicator method

- Not for imputation, but for building predictive models
- Only works for missing in covariates, not the target variables

Summary of ad-hoc imputation methods

• Note: the unbiasness of regression coefficients are assess with the variable containing missing values as the target variable

		Unbiased		Standard Error
	Mean	Reg Weight	Correlation	
Listwise	MCAR	MCAR	MCAR	Too large
Pairwise	MCAR	MCAR	MCAR	Complicated
Mean	MCAR	-	-	Too small
Regression	MAR	MAR	-	Too small
Stochastic	MAR	MAR	MAR	Too small
LOCF	-	-	-	Too small
Indicator	-	-	_	Too small

Table 1.1: Overview of assumptions made by ad-hoc methods.

Multiple imputation creates m > 1 complete datasets

- Three steps of multiple imputation
 - 1. Imputation
 - 2. Analysis: train separate models
 - 3. Pooling: variance among *m* parameter estimates combines the conventional sampling variance (within-imputation variance) and the extra variance caused by the missing data (between-imputation variance)



Incomplete data Imputed data Analysis results Pooled result Figure 1.6: Scheme of main steps in multiple imputation.

Why using multiple imputation?

- It provides a mechanism to deal with the inherent uncertainty of the imputations
- It separate the solution of the missing data problem from the solution of the complete-data problem (train predictive models on complete data)

Multiple imputation example using the mice package

```
## Load the mice package
library(mice);
## Impute 20 times, using preditive mean matching
imp <- mice(airquality, seed = 1, m = 20, print = FALSE)
## Fit linear regressions
fit <- with(imp, lm(Ozone ~ Wind + Temp + Solar.R))
## Pooled regression estimates
pander(summary(pool(fit)))
```

term	estimate	std.error	statistic	df	p.value
(Intercept)	-60.21	21.57	-2.791	100.3	0.006
Wind	-3.174	0.644	-4.927	83.29	0
Temp	1.584	0.228	6.959	125.7	0
Solar.R	0.058	0.023	2.454	79.63	0.016

References

- Van Buuren, S. (2018). Flexible Imputation of Missing Data, 2nd Edition. CRC press.
 - https://stefvanbuuren.name/fimd/