

Notes: Flexible Imputation of Missing Data – Ch2 Multiple Imputation

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Notations

- m : number of multiple imputations
- Y : data of the sample
 - Includes both covariates and response
 - Dimension $n \times p$
- R : observation indicator matrix, known
 - A $n \times p$ 0-1 matrix
 - $r_{ij} = 0$ for missing and 1 for observed
- Y_{obs} : observed data
- Y_{mis} : missing data
- $Y = (Y_{\text{obs}}, Y_{\text{mis}})$: complete data
- ψ : the parameter for the missing mechanism
- θ : the parameter for the full data Y

Concepts of MCAR, MAR, and MNAR, with notations

- Missing completely at random (MCAR)

$$P(R = 0 \mid Y_{\text{obs}}, Y_{\text{mis}}, \psi) = P(R = 0 \mid \psi)$$

- Missing at random (MAR)

$$P(R = 0 \mid Y_{\text{obs}}, Y_{\text{mis}}, \psi) = P(R = 0 \mid Y_{\text{obs}}, \psi)$$

- Missing not at random (MNAR)

$$P(R = 0 \mid Y_{\text{obs}}, Y_{\text{mis}}, \psi) \text{ does not simplify}$$

Ignorable

- The missing data mechanism is **ignorable** for likelihood inference (on θ), if
 1. MAR, and
 2. Distinctness: the parameters θ and ψ are independent (from a Bayesian's view)
- If the nonresponse is ignorable, then

$$P(Y_{\text{mis}} \mid Y_{\text{obs}}, R) = P(Y_{\text{mis}} \mid Y_{\text{obs}})$$

Thus, if the missing data model is ignorable, we can model θ just using the observed data

Goal of multiple imputation

- Note: for most multiple imputation practice, this goal is to train a (predictive) model with as small variances of the parameters as possible
- Q : estimand (the parameter to be estimated)
- \hat{Q} : estimate
 - Unbias

$$E(\hat{Q} | Y) = Q$$

- Confidence valid:

$$E(U | Y) \geq V(\hat{Q} | Y)$$

where U is the estimated covariance matrix of \hat{Q} , the expectation is over all possible samples, and $V(\hat{Q} | Y)$ is the variance caused by the sampling process

Within-variance and between-variance

$$E(Q | Y_{\text{obs}}) = E_{Y_{\text{mis}}|Y_{\text{obs}}} \{E(Q | Y_{\text{obs}}, Y_{\text{mis}})\}$$

$$V(Q | Y_{\text{obs}}) = \underbrace{E_{Y_{\text{mis}}|Y_{\text{obs}}} \{V(Q | Y_{\text{obs}}, Y_{\text{mis}})\}}_{\text{within-variance}} + \underbrace{V_{Y_{\text{mis}}|Y_{\text{obs}}} \{E(Q | Y_{\text{obs}}, Y_{\text{mis}})\}}_{\text{between variance}}$$

- Within-variance: average of the repeated complete-data posterior variance of Q , estimated by

$$\bar{U} = \frac{1}{m} \sum_{l=1}^m \bar{U}_l,$$

where \bar{U}_l is the variance of \hat{Q}_l in the l th imputation

- Between-variance: variance between the complete-data posterior means of Q , estimated by

$$B = \frac{1}{m-1} \sum_{l=1}^m (\hat{Q}_l - \bar{Q}) (\hat{Q}_l - \bar{Q})', \quad \bar{Q} = \frac{1}{m} \sum_{l=1}^m \hat{Q}_l$$

Decomposition of total variation

- Since \bar{Q} is estimated using finite m , the contribution to the variance is about B/m . Thus, the total posterior variance of Q can be decomposed into three parts:

$$T = \bar{U} + B + B/m = \bar{U} + \left(1 + \frac{1}{m}\right) B$$

- \bar{U} : the conventional variance, due to sampling rather than getting the entire population.
- B : the extra variance due to missing values
- B/m : the extra simulation variance because \bar{Q} is estimated for finite m
 - Traditionally choices are $m = 3, 5, 10$, but the current advice is to use a larger m , e.g., $m = 50$

Properness of an imputation procedure

- An imputation procedure is **confidence proper** for complete-data statistics \hat{Q}, U , if it satisfies the following three conditions approximately at large m

$$E(\bar{Q} | Y) = \hat{Q}$$

$$E(\bar{U} | Y) = U$$

$$\left(1 + \frac{1}{m}\right) E(B | Y) \geq V(\bar{Q})$$

- Here \hat{Q} is the complete-sample estimator of Q , and U is its covariance
- If we replace the \geq by $>$ in the third formula, then the procedure is said to be **proper**
- It is not always easy to check whether a procedure is proper.

Scope of the imputation model

- **Broad**: one set of imputations to be used for all projects and analyses
- **Intermediate**: one set of imputations per project and use this for all analyses
- **Narrow**: a separate imputed dataset is created for each analysis
- Which one is better: depends on the use case

Variance ratios

- Proportion of variation attributable to the missing data

$$\lambda = \frac{B + B/m}{T}$$

- If $\lambda > 0.5$, then the influence of the imputation model on the final result is larger than that of the complete-data model

- Relative increase in variance due to nonresponse

$$r = \frac{B + B/m}{\bar{U}} = \frac{\lambda}{1 - \lambda}$$

- Fraction of information about Q missing due to nonresponse

$$\gamma = \frac{r + 2/(\nu + 3)}{1 + r} = \frac{\nu + 1}{\nu + 3} \lambda + \frac{2}{\nu + 3}$$

- Here, ν is the degrees of freedom (see next)
- When ν is large, γ is very close to λ

Degrees of freedom (df)

- The degrees of freedom is the number of observations after accounting for the number of parameters in the model.
- The “old” formula (as in Rubin 1987): may produce values larger than the sample size in the complete data

$$\nu_{\text{old}} = (m - 1) \left(1 + \frac{1}{r^2} \right) = \frac{m - 1}{\lambda^2}$$

- Let ν_{com} be the conventional df in a complete-data inference problem. If the number of parameters in the model is k and the sample size is n , then $\nu_{\text{com}} = n - k$. The estimated observed data df that accounts for the missing information is

$$\nu_{\text{obs}} = \frac{\nu_{\text{com}} + 1}{\nu_{\text{com}} + 3} \nu_{\text{com}} (1 - \lambda)$$

- Barnard-Rubin correction: the adjusted df to be used for testing in multiple imputation is

$$\nu = \frac{\nu_{\text{old}} \nu_{\text{obs}}}{\nu_{\text{old}} + \nu_{\text{obs}}}$$

A numerical example

```
## Load the mice package
library(mice);
imp <- mice(nhanes, print = FALSE, m = 10, seed = 24415)
fit <- with(imp, lm(bmi ~ age))
est <- pool(fit); print(est, digits = 2)
```

```
## Class: mipo      m = 10
##           term  m estimate ubar    b    t dfcom    df  riv  l
## 1 (Intercept) 10     30.8  3.4 2.52 6.2    23  9.2 0.82
## 2           age 10     -2.3  0.9 0.39 1.3    23 12.3 0.48
```

- Columns ubar, b, and t are the variances
- Column dfcom is ν_{com}
- Column df is the Barnard-Rubin correction ν

T-test for regression coefficients

- Use the Barnard-Rubin correction of ν as the shape parameter of t-distribution.

```
print(summary(est, conf.int = TRUE), digits = 1)
```

```
##           term estimate std.error statistic df p.value 2.5
## 1 (Intercept)      31         2         12  9  5e-07
## 2           age      -2         1         -2 12  7e-02
```

Imputation evaluation criteria

- The following criteria are useful in simulation studies (when you know the true Q)
1. Raw bias (RB): upper limit 5%

$$\text{RB} = \left| \frac{E(\bar{Q}) - Q}{Q} \right|$$

2. Coverage rate (CR): A CR below 90% for the nominal 95% interval is bad
3. Average width (AW) of confidence interval
4. Root mean squared error (RMSE): the smaller the better

$$\text{RMSE} = \sqrt{(E(\bar{Q}) - Q)^2}$$

Imputation is not prediction

- Shall we evaluate an imputation method by examine how it can closely recover the missing values?
 - For example, using the RMSE to see if the imputed values \hat{y}_i are close to the true (removed) missing data y_i^{mis} ?

$$\text{RMSE} = \sqrt{\frac{1}{n_{\text{mis}}} \sum_{i=1}^{n_{\text{mis}}} (y_i^{\text{mis}} - \hat{y}_i)^2}$$

- NO! This will favor least squares estimates, and it will find the same values over and over; and thus it is single imputation. This ignores the inherent uncertainty of the missing values.

When not to use multiple imputation

- For predictive modeling, if the missing values are in the target variable Y , then complete-case analysis and multiple imputation are equivalent.
- Two special cases where listwise deletion is better than multiple imputation
 1. If the probability to be missing does not depend on Y
 2. If the complete data model is logistic regression, and the missing data are confined to Y , not X

References

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 - <https://stefvanbuuren.name/fimd/>
- Rubin, D. (1987). Multiple Imputation for Nonresponse in Surveys. New York: John Wiley & Sons.